# M12 Lexium MDrive®

## Simplifying machine building with compact integrated motors



Programmable Motion Control version: M12 connectors & IP65 rating Integrated stepper motors with on-board programmable motion controller for stand-alone operation and closed loop performance

CE KIR REACH IP65



### Description

### M12 Lexium MDrive® Motion Control

Fully programmable, RS-422/485 IP65-rated integrated 2-phase stepper motor

CE KIR REACH IP65



- rotary stepper motor
- 2 M12 sealed circular connectors and IP65 certified protection
- 3 microstepping drive
- 4 programmable motion controller
- 5 up to 8 I/O lines
- 6 internal encoder option
- 7 closed loop performance

#### **Product offer**

M12 Lexium MDrive® Motion Control products are certified with an IP65 rating against water and dust ingress. These integrated high-torque 1.8° 2-phase stepper motors include on-board I/O and fully programmable motion controller, drive electronics, and closed loop performance with internal encoder option. This means programmable Motion Control products are stand-alone motion control solutions that can be used without an external controller.

M12 Lexium MDrive Motion Control products (LMD•M•C) have an RS-422/485 serial interface. Programming is with MCode, simple 1 to 2 character instructions, using the Lexium MDrive Software Suite provided free of charge. An optional Communication Converter Kit (part # MD-CC405-000) is recommended to facilitate prototyping.

Closed loop products (LMDCM•C) are equipped with 1000 line (4000 count/rev) encoders internal to the unit, requiring no extra space in an application. Encoders perform stall detection, position maintenance and find index mark, in addition to monitoring motor shaft position for real time closed loop feedback accomplished with hMTechnology.

Unlike traditional motor systems, hMT combines the best of servo and stepper motor technologies, while delivering unique capabilities and enhancements over both, including: – real time closed loop control – no loss of synchronization/stalling

- full use of motor torque
- torque mode control
- reduced motor heat (1)
- lower energy consumption (1)
- Application areas

Lexium MDrive Motion Control products with circular connectors are ideal for machine builders who want an optimized motor with on-board electronics in a robust, sealed package. LMD closed loop products deliver enhanced performance, providing a lower cost option to servo motors in many applications. Integrated electronics of the fully programmable Lexium MDrive Motion Control products also reduce the potential for problems due to electrical noise by eliminating cabling between motor and drive.

These compact, powerful and cost effective motion control solutions deliver unsurpassed smoothness and performance that will reduce system cost, design and assembly time for a large range of motion applications.

#### **Features**

- Integrated microstepping drive and high torque 1.8° 2-phase NEMA stepper motor
- Fully programmable integrated motion controller
- M12 sealed circular connectors
- IP65 certified protection
- Closed loop control with 1000 line internal encoder and hMTechnology (optional)
   Prevents motor stalling while delivering numerous performance advantages
- Variable current control reduces motor heat and lowers energy consumption
- Advanced current control for exceptional performance and smoothness
- RS-422/485 serial interface
- +12 up to +70 VDC input power range
- Cost effective
- Extremely compact
- Up to 8 I/O
  - Up to four +5 to +24 VDC signal inputs
  - One 12 bit analog input
  - Two 100mA power outputs (only LMD57 & LMD85 products)
  - One 5.5mA high-speed signal output
  - Auxiliary logic power supply input
- 20 microstep resolutions to 51,200 steps/rev including: Degrees, Metric, Arc Minutes
- Programmable motor run and hold currents
- 62 software addresses for multi-drop communications
- 336 user program labels / 11,120 bytes flash memory
- 0 to 2.56 MHz step clock rate selectable in 0.59 Hz increments
- Motor stack lengths: single, double and triple
- Graphical user interface provided for quick and easy configuration

(1) Achieved with hMTechnology variable current control.



### M12 Lexium MDrive® Motion Control

Fully programmable, RS-422/485 IP65-rated integrated 2-phase stepper motor

|                  |                                  |                                | LMD•M42•C (NEMA17)   | LMD•M57•C (NEMA23)                                   | LMD•M85•C (NEMA34            |  |  |
|------------------|----------------------------------|--------------------------------|--|--|------------------------------|--|--|
| Input power      | Voltage                          |                                | +12+48 VDC   | +12+60 VDC   | +12+70 VDC                   |  |  |
|                  | Current maximum (1)              |                                | 2.5 A  | 3.5 A  | 4.0A                         |  |  |
| /O sourcing or   | Number of I/O                    | Analog input                   | 1  | 1  | 1                            |  |  |
| sinking          |                                  | Signal inputs                  | 3  | 4  | 4                            |  |  |
|                  |                                  | Power outputs                  | 0  | 2  | 2                            |  |  |
|                  |                                  | Signal outputs                 | 1  | 1  | 1                            |  |  |
|                  | Analog input                     | Resolution                     | 12 bit   |  |                              |  |  |
|                  | 0                                | Voltage range                  | 0+5 VDC, 0+10 VDC,   | , 020 mA, 420 mA                                     |                              |  |  |
|                  | Signal inputs                    | Voltage range                  | +5 +24 VDC, TTL level c  | ompatible  |                              |  |  |
|                  | 0                                | Protection                     | over temp, short circuit, tr   | ansient, over voltage, induc                         | ctive clamp                  |  |  |
|                  | Power outputs                    | Current rating                 | -100+100mA   | , , ,  | I                            |  |  |
|                  | ·                                | Voltage range                  | -24+24 VDC   |  |                              |  |  |
|                  | High-speed signal output         | Current open collector/emitter | 5.5 mA   |  |                              |  |  |
|                  | 5 1 5 1                          | Voltage open collector         | +60 VDC  |  |                              |  |  |
|                  |                                  | Voltage open emitter           | +7 VDC   |  |                              |  |  |
| Thermal          | Operating temp                   | Heat sink maximum              | 85°C   |  |                              |  |  |
|                  | non-condensing                   | Motor maximum                  | 100°C  |  |                              |  |  |
| Protection       | Туре                             | Temp warning                   | 084°C, user selectable   |  |                              |  |  |
|                  |                                  | Earth grounding                | via product chassis ground lug   |  |                              |  |  |
|                  |                                  | IP rating                      | IP65   |  |                              |  |  |
| Aux. logic input | Voltage range (2)                |                                | +12+24 VDC   |  |                              |  |  |
| Communication    | Туре                             |                                | RS-422/485   |  |                              |  |  |
|                  | Baud rate                        |                                | 4.8115.2 kbps  |  |                              |  |  |
| Notion           | Microstep resolution             | Number of settings             | 20   |  |                              |  |  |
|                  | ·                                | Steps per revolution           | 200, 400, 800, 1000, 1600, 2000, 3200, 5000, 6400, 10000, 12800, 20000, 25000, 25600, 40000, 50000, 51200, 36000 (0.01 deg/µstep), 21600 (1 arc minute/µstep), 25400 (0.001mm/µstep) |  |                              |  |  |
|                  | Encoder (3)                      | Line count                     | 1000 lines/4000 edges pe   | er rev   |                              |  |  |
|                  |                                  | Style                          | internal, magnetic position, encoder/32 bit  |  |                              |  |  |
|                  | Counters                         | Туре                           |  |  |                              |  |  |
|                  |                                  | Edge rate maximum              | 5 MHz  |  |                              |  |  |
|                  | Velocity                         | Range                          | +/- 2,560,000 steps per se   | econd  |                              |  |  |
|                  |                                  | Resolution                     | 0.5961 steps per second  |  |                              |  |  |
|                  | Accel/Decel                      | Range                          | 1.5 x 109 steps per second   | d <sup>2</sup>                                       |                              |  |  |
|                  |                                  | Resolution                     | 90.9 steps per second <sup>2</sup>   |  |                              |  |  |
| Software         | Program storage                  | Type/size                      | flash / 11,120   |  |                              |  |  |
|                  | User registers                   |                                | four 32 bit  |  |                              |  |  |
|                  | User program labels & variat     | bles                           | 336  |  |                              |  |  |
|                  | Math functions                   |                                | $+,-,x,\div,>,<,=,<=,>=,$  | AND, OR, XOR, NOT                                    |                              |  |  |
|                  | Branch functions                 |                                | Branch and Call  |  |                              |  |  |
|                  | General purpose<br>I/O functions | Inputs                         | home, limit plus, limit minus, go, stop, pause, jog plus, jog minus, reset, captu general purpose  |  |                              |  |  |
|                  |                                  | Outputs                        | moving, error, stall, velociposition, hMT active, mak  | ty change, general purpose<br>e up active, attention | e, locked rotor, moving to   |  |  |
|                  | Trip functions                   |                                | trip on input, trip on position  | on, trip on time, trip capture                       | e, trip on relative position |  |  |
|                  | Party mode addresses             |                                | 62   |  |                              |  |  |
|                  | Encoder functions                |                                | stall detection, position ma   | aintenance, find index                               |                              |  |  |

(1) Actual power supply current will depend on voltage and load.
 (2) When input voltage is removed, maintains power only to control and feedback circuits.
 (3) Only with Lexium MDrive closed loop/encoder products.

An optional Communication Converter Kit is recommended to facilitate prototyping.

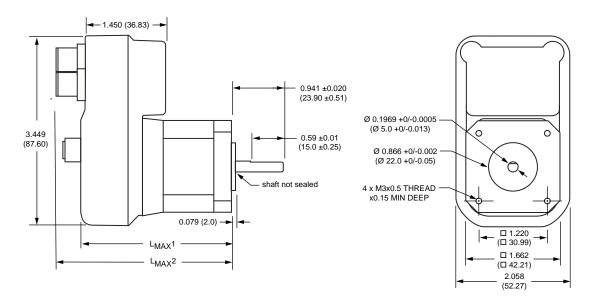


### Dimensions

### M12 Lexium MDrive® Motion Control

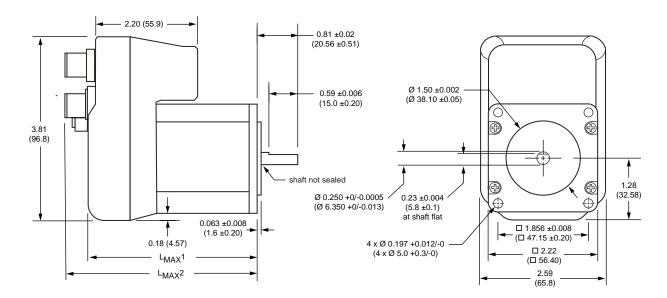
Fully programmable, RS-422/485 IP65-rated integrated 2-phase stepper motor

### **LMD**•42•C NEMA17 motor – dimensions in inches (mm)



| Motor stack length | Lmax1       | Lmax2        |
|--------------------|-------------|--------------|
| Single             | 2.78 (70.7) | 3.39 (86.0)  |
| Double             | 2.98 (75.7) | 3.58 (91.0)  |
| Triple             | 3.33 (84.7) | 3.94 (100.0) |

### LMD•57•C NEMA23 motor - dimensions in inches (mm)



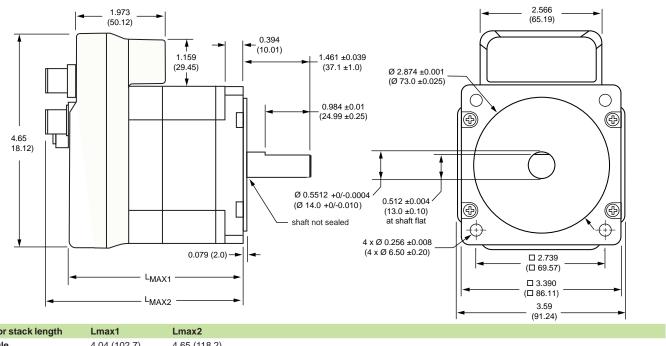
| Motor stack length | Lmax1        | Lmax2        |
|--------------------|--------------|--------------|
| Single             | 3.22 (81.8)  | 3.83 (97.3)  |
| Double             | 3.56 (90.4)  | 4.21 (106.9) |
| Triple             | 4.44 (112.7) | 5.06 (128.5) |

### Dimensions

### M12 Lexium MDrive® Motion Control

Fully programmable, RS-422/485 IP65-rated integrated 2-phase stepper motor

### LMD-85-C NEMA34 motor - dimensions in inches (mm)



| Motor stack length | Lmax1        | Lmax2        |
|--------------------|--------------|--------------|
| Single             | 4.04 (102.7) | 4.65 (118.2) |
| Double             | 4.57 (116.2) | 5.18 (131.7) |
| Triple             | 6.14 (156.1) | 6.75 (171.5) |



## Connectivity and signal indicators

### M12 Lexium MDrive® Motion Control

Fully programmable, RS-422/485 IP65-rated integrated 2-phase stepper motor

### **Software interface**

The free Lexium MDrive Software Suite includes a user interface GUI for product commissioning and programming via a PC.

PC interface is easily accomplished using the USB to RS-422/485 Communication Converter Kit (part # MD-CC405-000). Compatible with 32- and 64-bit Windows, Mac OS, and Linux operating systems. Each kit includes a communication converter and 5.0'/1.5m cordset with M12 mating connector.

### Connectors

All Lexium MDrive connectors are conveniently grouped on the back of each product. Circular M12 connectors are used consistently on all motor sizes, with gender and keying features for correct connecting. Cordsets and a Communication Converter Kit are available to facilitate rapid prototyping.

A #6-32 screw lug is provided for earth grounding.

| Connector      | Style            | Assignment                      |
|----------------|------------------|---------------------------------|
| P1             | M12 4-pin male   | Supply voltage                  |
| P2             | M12 12-pin male  | I/O and multifunction interface |
| P3             | M12 5-pin female | Communication                   |
| Chassis ground | #6-32 screw lug  | Earth grounding                 |

### **Status indicators**

Lexium MDrive products include 2 LED signal indicators. The multi-color LEDs are programmed to indicate a range of pre-defined messages to aid users. See product user manual for details.



P2: I/O & multifunction M12 12-pin male

### Part numbers

### M12 Lexium MDrive® Motion Control

Fully programmable, RS-422/485 IP65-rated integrated 2-phase stepper motor



LMD•M85•C

LMD•M57•C

| Part numbers  |   |   |   |   |   |   |   |   |   |
|---|---|---|---|---|---|---|---|---|---|
| Example   | L | Μ | D | С | Μ | 4 | 2 | 1 | С |
| Product<br>LMD = Lexium MDrive  | L | М | D | С | Μ | 4 | 2 | 1 | С |
| Control type<br>C = Closed loop / with hMT and encoder (1)<br>O = Open loop / no hMT or encoder | L | Μ | D | С | М | 4 | 2 | 1 | С |
| Communication type<br>M = Motion Control via RS-422/485 serial interface                        | L | Μ | D | С | М | 4 | 2 | 1 | С |
| Flange size<br>42 = NEMA 17 / 42mm<br>57 = NEMA 23 / 57mm<br>85 = NEMA 34 / 85mm                | L | Μ | D | С | М | 4 | 2 | 1 | С |
| Motor length<br>1 = single stack<br>2 = double stack<br>3 = triple stack                        | L | Μ | D | С | Μ | 4 | 2 | 1 | С |
| Variation<br>C = M12 circular connectors and IP65 rating  | L | Μ | D | С | Μ | 4 | 2 | 1 | С |

(1) Closed loop control delivers encoder feedback and hMT enhanced motor performance.









| Installation accessories  |        |        |              |
|---|--------|--------|--------------|
| Description   | Length | Length | Reference    |
|   | m      | feet   |              |
| Communication converter kit, USB to RS  |        |        |              |
| For RS-422/485 products. USB-pluggable converter to set/program communication parameters in 32- or 64-bit. Kit includes communication converter and pre-wired shielded cable with M12 mating connector. |        |        |              |
| <ul> <li>Mates to M12 5-pin female communication connector</li> </ul>   | 1.5    | 5.0    | MD-CC405-000 |
|   |        |        |              |

| Communication cordset   |     |      |              |
|---|-----|------|--------------|
| Shielded cable with straight M12 5-pin male connector.                |     |      |              |
| <ul> <li>Mates to M12 5-pin female communication connector</li> </ul> | 3.0 | 10.0 | MD-CS600-000 |
|   |     |      |              |
|   |     |      |              |

| Power cordset   |     |      |              |
|---|-----|------|--------------|
| Pre-wired shielded cable with straight M12 connector. |     |      |              |
| Mates to M12 4-pin male power connector               | 3.0 | 10.0 | MD-CS620-000 |
|   |     |      |              |

3.0

10.0

### I/O cordset

| Pre-wired shielded cable with straight M12 connector. |
|---|
|---|

Mates to M12 12-pin male I/O connector

MD-CS610-000

### System performance

## Lexium MDrive® Motor specifications

| LMD•42 NEMA 17 motor specifications |                        |               |        |        |  |  |  |  |
|-------------------------------------|------------------------|---------------|--------|--------|--|--|--|--|
|                                     | Motor stack length     | Single Double |        | Triple |  |  |  |  |
| Helding termine                     | oz-in                  | 43.9          | 58.1   | 87.8   |  |  |  |  |
| Holding torque                      | N-cm                   | 31            | 41     | 62     |  |  |  |  |
| Detent termin                       | oz-in                  | 1.7           | 2.1    | 3.5    |  |  |  |  |
| Detent torque                       | N-cm                   | 1.2           | 1.5    | 2.5    |  |  |  |  |
| Rotor inertia                       | oz-in-sec <sup>2</sup> | 0.0005        | 0.0008 | 0.0012 |  |  |  |  |
| Rotor mertia                        | kg-cm <sup>2</sup>     | 0.038         | 0.057  | 0.082  |  |  |  |  |
| Dediel lead limit senter of shott   | lbs                    | 8.5           | 8.5    | 8.5    |  |  |  |  |
| Radial load limit, center of shaft  | kg                     | 3.8           | 3.8    | 3.8    |  |  |  |  |
| Axial load limit                    | lbs                    | 10            | 10     | 10     |  |  |  |  |
| @ 1500 rpm (5000 full steps/sec)    | kg                     | 4.5           | 4.5    | 4.5    |  |  |  |  |
| Weight (motor+driver)               | oz                     | 13.6          | 16.0   | 18.4   |  |  |  |  |
| weight (motor fullver)              | g                      | 385           | 454    | 522    |  |  |  |  |

### LMD•57 NEMA 23 motor specifications

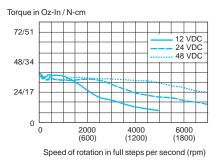
|                                    | Motor stack length     | Single | Double | Triple |
|------------------------------------|------------------------|--------|--------|--------|
| Helding termine                    | oz-in                  | 103.4  | 158.6  | 242.2  |
| Holding torque                     | N-cm                   | 73.0   | 112.0  | 171.0  |
| Detent torgue                      | oz-in                  | 3.9    | 5.6    | 9.72   |
| Detent torque                      | N-cm                   | 2.7    | 3.9    | 6.86   |
| Rotor inertia                      | oz-in-sec <sup>2</sup> | 0.0025 | 0.0037 | 0.0065 |
| Rotor mertia                       | kg-cm <sup>2</sup>     | 0.18   | 0.26   | 0.46   |
| Radial load limit, center of shaft | lbs                    | 15     | 15     | 15     |
| Radial load limit, center of shart | kg                     | 6.8    | 6.8    | 6.8    |
| Axial load limit                   | lbs                    | 20     | 20     | 20     |
| @ 1500 rpm (5000 full steps/sec)   | kg                     | 9      | 9      | 9      |
| Weight (motor+driver)              | oz                     | 26.4   | 31.2   | 44.0   |
| weight (motor+driver)              | g                      | 748    | 885    | 1247   |

| LMD•85 NEMA34 motor specifications                   |                    |        |        |        |
|--|--------------------|--------|--------|--------|
|  | Motor stack length | Single | Double | Triple |
| Holding torque                                       | oz-in              | 336.0  | 480.0  | 920.0  |
|  | N-cm               | 237.0  | 339.0  | 650.0  |
| Detent torque  | oz-in              | 10.9   | 14.16  | 19.83  |
|  | N-cm               | 7.7    | 10.0   | 14.0   |
| Rotor inertia  | oz-in-sec2         | 0.0127 | 0.0191 | 0.0382 |
|  | kg-cm <sup>2</sup> | 0.90   | 1.35   | 2.70   |
| Radial load limit, center of shaft                   | lbs                | 65     | 65     | 65     |
|  | kg                 | 29.4   | 29.4   | 29.4   |
| Axial load limit<br>@ 1500 rpm (5000 full steps/sec) | lbs                | 20     | 20     | 20     |
|  | kg                 | 9      | 9      | 9      |
| Weight (motor+driver)                                | lb                 | 4.45   | 5.65   | 9.0    |
|  | kg                 | 2.02   | 2.56   | 4.08   |

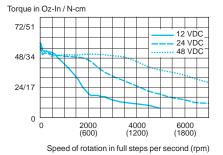


### Lexium MDrive® Speed torque characteristics

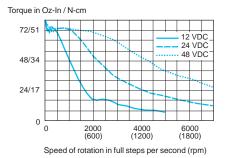
#### LMD-42 NEMA 17 speed torque (1) Single stack length



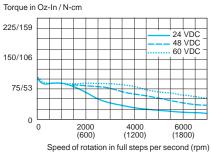
#### **Double stack length**



#### **Triple stack length**



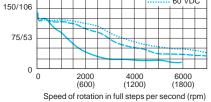
#### LMD•57 NEMA 23 speed torque (1) Single stack length



225/159

**Double stack length** 

Torque in Oz-In / N-cm



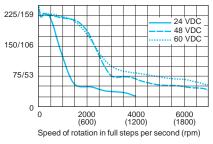
#### **Triple stack length**



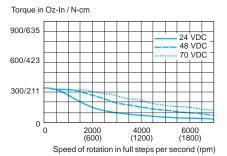
24 VDC

48 VDC

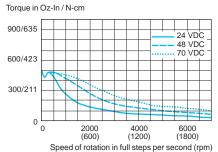
60 VDC



#### LMD•85 NEMA34 speed torque (2) Single stack length

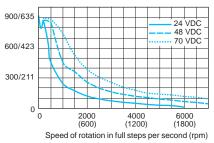


**Double stack length** 



### **Triple stack length**

Torque in Oz-In / N-cm



(1) Test conditions: 100% current, 0.84oz. damper, 0.18589 oz-in² inertia, hMT off (2) Test conditions: 100% current, 3.7 oz. damper, 4.75670 oz-in² inertia, hMT off

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